# Hyunin Lee

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#### Education

University of California, Berkeley

Ph.D. in Mechanical Engineering / Specialization: Reinforcement Learning

Seoul National University B.S in Mechanical Engineering; summa cum laude CA, United States Aug. 2022 –

Seoul, Rep.of.Korea Mar. 2015 – Feb. 2022

Publications / C: Conference, J: Journal, P: Preprint

[C5] Position: AI Safety Must Embrace an Antifragile Perspective.M. Jin, H. Lee. Under Revision for ICML. 2025. [pdf]

[C4] A Black Swan Hypothesis: The Role of Human Irrationality in AI Safety.H. Lee, C. Park, D. Abel, M. Jin. *ICLR*. 2025. [pdf]

[C3] Pausing Policy Learning in Non-stationary Reinforcement Learning.
 H. Lee, M. Jin, J. Lavaei, and S. Sojoudi. *ICML*. 2024. (Oral, Top 1.2%) [pdf/codes/talk]

[J3] Policy-based Primal-Dual Methods for Concave CMDP with Variance Reduction.
D. Ying, M. Guo, H. Lee, Y. Ding, J. Lavaei, and Z. Shen. Under Revision for JAIR. 2024. [pdf /codes]

[C2] Tempo Adaptation in Non-stationary Reinforcement Learning.
 H. Lee, Y. Ding, J. Lee, M. Jin, J. Lavaei, and S. Sojoudi. NeurIPS. 2023 [pdf/codes/slides]

[J2] Beyond Exact Gradients: Convergence of Stochastic Soft-Max Policy Gradient Methods with Entropy Regularization.

Y. Ding, J. Zhang, H. Lee, and J. Lavaei. IEEE TAC. 2024 [pdf]

[C1] Initial State Interventions for Deconfounded Imitation Learning.
 S. Pfrommer, Y. Bai, H. Lee, and S. Sojoudi. *IEEE CDC*. 2023. [pdf]

[J1] Explainable Deep Learning Model for EMG Based Finger Angle Estimation Using Attention. H. Lee, D. Kim, and Y. Park. *IEEE TNSRE*. vol. 30, pp. 1877-1886 2022. [pdf/codes]

## Work Experience

University of California, Berkeley	Aug. 2022 –	
Graduate Student Reseacher	Advisor: Prof. Somayeh Sojoudi	
• Research on <b>non-stationary reinforcement learning</b> and <b>optimization</b> for distributional shift data.		
OUTTA / [Homepage/ Linkedin]	Aug. 2021 –	
Co- $Founder$	South Korea	
• Provide an online AI education lecture to over <b>200+ underprivileged students</b> in South Korea every year.		
Knowledge AI	Jul. 2021 – Jul.2022	
Machine Learning Engineer	Boston,MA	
• Develop a <b>bayesian inference algorithm</b> that quantifies students' understanding of math topics using Python		
	learning system using python.	
Seoul National University	Mar. $2021 - Nov. 2021$	
Undergraduate Research Intern	Soft Robotics & Bionics Lab	
• Propose attention-based sequential decision making algorithm to predict finger angles based on muscle activation on forearm using Python. Improved prediction accuracy over 10 $\%$		
Seoul National University	Sep. 2020 – Jun. 2021	
Undergraduate Research Intern	Robot Learning Lab	
• Develop deep generative Q learning algorithm to reconstruct a reward kernel using Python [pdf] [video]		

## Academic Activitiy

Reviewer Program Chair Committee	viewer ICLR 2024-2025, ICML 2024-2025, NeurIPS 2024, RLC 2025, AISTATS 2025 ogram Chair Committee AAAI 2025	
Teaching Experience		
Graduate Student Instructo	or, Statistics and Data Science for Engineers	Spring 2025
Graduate Student Instructo	or, Dynamic Systems and Feedback	Fall 2024
Teaching Tutor, Math and	Physics for Freshman	Spring 2019, Spring 2020
Teaching Assistant, Dynam	ic	Fall 2019
Teaching Assistant, Mechan	nical Product Design	Fall 2020
Grants and Honors		
Berkeley Summer Research	Fellowship   Mechanical Engineering Department	Summer 2024
NeurIPS scholar award   Co	nference on Neural Information Processing Systems	Dec. 2023
Kwanjeong Abroad Scholar	${f ship} \mid \mathit{Kwanjeong} \ \mathit{Educational} \ \mathit{Foundation}$	Fall 2022 – Present
Berkeley Fellowship for Gra	$\mathbf{duate \ Study} \mid \mathit{Graduate \ Division}$	Fall 2022 – Spring 2023
National Science & Technol	ogy Scholarship   Korea Student Aid Foundation	Spring 2017, Fall 2019
		Spring 2020, Fall 2020
Certificate of Appreciation	(OUTTA)   Dean, college of Engineering, Seoul Nation	al University Jun. 2021
Scholarship to Academic Ex	ccellence   Seoul National University	Spring 2015, Fall 2015
		Spring 2016, Fall 2016

## Graduate courses

Specialization: Non-convex Optimization & Reinforcement Learning

Theoretical statistics I, II, Probability Theory I, II
Convex Optimization (convex optimization, robust optimization)
Mathematical Programming II (Advanced optimization theory, non-convex optimization)
Advanced control system I (canonical state-space representation forms, Lyapunov stability, LQR control)
Experiential advanced control design I, II (model predictive control, kalman filter)
Linear System, Nonlinear System

## Technical Skills

Languages: Python (Advanced), MatLab (Advanced), C++ Software library, platform : Pytorch (Advanced), Tensorflow. Gurobi (Advanced), CPLEX (Advanced)