Hyunin Lee

Email: hyunin@berkeley.edu | <u>linkedin</u> | github | homepage

Education

University of California, Berkeley

CA, United States

Ph.D. in Mechanical Engineering / Specialization: Reinforcement Learning

Aug. 2022 -

Seoul National University

Seoul, Rep. of. Korea

B.S in Mechanical Engineering; summa cum laude

Mar. 2015 - Feb. 2022

Publications

[C2] Tempo Adaptation in Non-stationary Reinforcement Learning.

H. Lee, Y. Ding, J. Lee, M. Jin, J. Lavaei, and S. Sojoudi. NeurIPS. 2023 [pdf/codes/slides]

[J1] Beyond Exact Gradients: Convergence of Stochastic Soft-Max Policy Gradient Methods with Entropy Regularization.

Y. Ding, J. Zhang, H. Lee, and J. Lavaei. Under revision for *IEEE TAC* [pdf]

[C1] Initial State Interventions for Deconfounded Imitation Learning.

S. Pfrommer, Y. Bai, H. Lee, and S. Sojoudi. *IEEE CDC*. 2023. [pdf]

[J1] Explainable Deep Learning Model for EMG Based Finger Angle Estimation Using Attention.

H. Lee, D. Kim, and Y. Park. *IEEE TNSRE*. vol. 30, pp. 1877-1886 2022. [pdf/codes]

Work Experience

University of California, Berkeley

Aug. 2022 -

Graduate Student Reseacher

Advisor: Prof. Javad Lavaei, Prof. Somayeh Sojoudi

• Research on non-stationary reinforcement learning and non-convex optimization for distributional shift data.

Knowledge AI

 $Jul.\ 2021-Jul.2022$

Machine Learning Engineer

Boston MA

- Develop a Bayesian inference algorithm that quantifies students' understanding of each math topic using Python
- Develop question-recommendation deep learning algorithm on Math online learning system using python.

Seoul National University

Mar. 2021 - Nov. 2021

Undergraduate Research Intern

Soft Robotics & Bionics Lab

• Propose attention based deep learning algorithm to predict finger angles based on muscle activation on forearm using Python. Improved prediction accuracy over 10 %

Seoul National University

Sep. 2020 – Jun. 2021

 $Undergraduate\ Research\ Intern$

Robot Learning Lab

• Develop deep Q-learning algorithm that utilizes VAE-GAN as a reward kernel using Python [pdf] [video]

Scholarships and Honors

NeurIPS scholar award | Conference on Neural Information Processing Systems

2023

Kwanjeong Abroad Scholarship | Kwanjeong Educational Foundation

Fall 2022 - Present

Berkeley Fellowship for Graduate Study | Graduate Division

Fall 2022 - Present

Graduate courses

Specialization: Non-convex Optimization & Reinforcement Learning

Theoretical statistics I, II

Convex Optimization (convex optimization, robust optimization)

Advanced control system I (canonical state-space representation forms, Lyapunov stability, LQR control)

Experiential advanced control design I, II (model predictive control, kalman filter)

Technical Skills

Languages: Python (Advanced), MatLab (Advanced), C++

Software library, platform: Pytorch (Advanced), Tensorflow. Gurobi, CPLEX